

Bootup automatic process for RMS and CVR with pipewire.

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Introduction

This page dedicated to bringing up and validation of RMS and CVR use case with bootup service file.

RMS: The RDKC Media Server is much more than a multi-format, multi-protocol server that delivers your media rich content across multiple screens and platforms. The RDK camera software runs on RPi-0/RPI-3 device. With RTSP streaming we can able to play live streaming content in VLC player.

CVR: It using pipewire callback to receive frames from v4l2 and also it using AWS Kinesis Video Stream(KVS) to perform 24/7 video recording with AWS IOT credential.

Build and Flash Procedure

Refer below link to build camera image

Morty:

[RDK-C Build Instruction for RPI-0](#)

[RDK-C Build Instruction for RPI-3](#)

Dunfell:

[RDK-C rdk-next Yocto 3.1 dunfell build for Raspberrypi](#)

Fresh Bootup Setup

STEP 1:

Add require SSID and PSK in /etc/wpa_supplicant.conf file in below format

```
network={
ssid="username"
psk="password"
}
```

Console output

```
ctrl_interface=/var/run/wpa_supplicant
ctrl_interface_group=0
update_config=1

network={
ssid="XXXX"
psk="YYYYYYYYYY"
}
```

STEP 2:

AWS Account and IOT credential creation steps

1.AWS account is needed for to validate CVR use case. so, Refer below link to create AWS account.

[Procedure To Create AWS Account](#)

After the AWS account creation, Refer same link to create Access key ID ,Secret Access Key and Region Name of your AWS account.

2. After the AWS account creation, Need to create IOT credential with AWS CLI interface to validate CVR use case.

Use the below link to install AWS CLI interface package for to create AWS IOT credential.

Please install this AWS CLI package in your local linux pc. we can interact AWS account through our local linux pc with this AWS CLI interface.

<https://docs.aws.amazon.com/cli/latest/userguide/install-cliv2-linux.html#cliv2-linux-install>

Follow the below command to create config and credentials file in your local PC to interact AWS account

AWS Configure

```
$ aws configure

AWS Access Key ID [None]: XXXXXXXXXX      ( Give your AWS account Access Key ID )
AWS Secret Access Key [None]: YYYYYYYYYYYY ( Give your AWS Secret Key )
Default region name [None]: ZZZZZZZZZZ ( Give your Region Name )
Default output format [None]: json
```

Oncw you done this **aws configure** in your local PC automatically below files will be create with below content. so, please cross check whether that is created or not

AWS Configure

```
vi ~/.aws/config

[default]
region = ZZZZZZZZZZ
output = json
```

AWS Configure

```
vi ~/.aws/credentials

[default]
aws_access_key_id = XXXXXXXXXX
aws_secret_access_key = YYYYYYYYYYYY
```

use the below link to create AWS IOT credential

<https://docs.aws.amazon.com/kinesisvideostreams/latest/dg/how-iot.html>

After created the IOT credential you will get below list of details

Stream Name, Default Region, IOT Credential Endpoint, Certificate key, Private Kay, Role Alias and cacertificate key

Move the certificate.pem,private.pem.key and cacert.pem keys into your RPI /etc/ssl/certs/ directory

STEP 3:

Copy certificate.pem,private.pem.key and cacert.pem keys into your RPI /etc/ssl/certs/ directory

Give AMS STREAM_NAME,AWS_DEFAULT_REGION,IOT_GET_CREDENTIAL_ENDPOINT and ROLE_ALIAS values in your RPI /usr/local/cvr/cvr.conf file

STEP 4:

Reboot the Target

After Reboot don't do step 1 to 4.

Note : Step 1 to 4 is only applicable for fresh target boot-up with new image.

RMS & CVR Validation

STEP 1:

WiFi/Ethernet connection is must needed for validation

Check WiFi/Ethernet connection by using below command.

ifconfig

Console output

```
root@raspberrypi3-rdk-camera:~# ifconfig
eth0      Link encap:Ethernet  HWaddr B8:27:EB:87:67:91
          UP BROADCAST MULTICAST  MTU:1500  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)

lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          UP LOOPBACK RUNNING  MTU:65536  Metric:1
          RX packets:89842 errors:0 dropped:0 overruns:0 frame:0
          TX packets:89842 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:25639748 (24.4 MiB)  TX bytes:25639748 (24.4 MiB)

wlan0     Link encap:Ethernet  HWaddr B8:27:EB:D2:32:C4
          inet addr:192.168.43.146  Bcast:192.168.43.255  Mask:255.255.255.0
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:44 errors:0 dropped:0 overruns:0 frame:0
          TX packets:103 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:4484 (4.3 KiB)  TX bytes:10216 (9.9 KiB)
```

STEP 2:

check loaded module by using below command

lsmod

Console output

```
root@raspberrypi3-rdk-camera:~# lsmod
Module                Size  Used by
bcm2835_v4l2          40563   0
v4l2_common            4809   1 bcm2835_v4l2
videobuf2_vmalloc      6264   1 bcm2835_v4l2
videobuf2_memops       1528   1 videobuf2_vmalloc
videobuf2_v4l2        12640   1 bcm2835_v4l2
videobuf2_core        27389   2 bcm2835_v4l2,videobuf2_v4l2
videodev             154457   4 v4l2_common,videobuf2_core,bcm2835_v4l2,videobuf2_v4l2
media                 23307   1 videodev
brcmfmac             258239   0
brcmutil              7590   1 brcmfmac
snd_bcm2835           21405   0
cfg80211             492836   1 brcmfmac
snd_pcm               79872   1 snd_bcm2835
rfkill               19936   3 cfg80211
snd_timer             20294   1 snd_pcm
snd                   52949   3 snd_timer,snd_bcm2835,snd_pcm
lirc_rpi              6840   0
lirc_dev              7533   1 lirc_rpi
uio_pdrv_genirq       3469   0
uio                   8703   1 uio_pdrv_genirq
fixed                 2876   0
sch_fq_codel          9662   2
ipv6                 384101  18
```

STEP 3:

check camera device there or not by using below command

ls /dev/video0

Console output

```
root@raspberrypi0-rdk-camera:~# ls /dev/video0
/dev/video0
```

STEP 4:

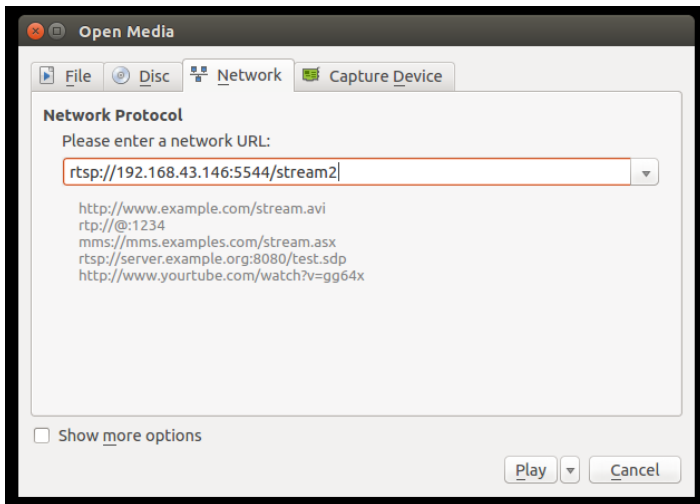
RMS Output

On VLC player, for RTSP streaming

need to enter media Open Network Stream option and then give rtsp URL to play streaming content in VLC

rtsp://camera_ip:5544/stream2

Example :<rtsp://192.168.43.146:5544/stream2>



We can able to see the live streaming content on VLC Player.

Note: VLC player available PC and RPI target should run in same network.

STEP 5:

CVR Output

Enter into AWS account and select the corresponding video stream service which was we created for streaming.

Press "Media Playback" option on the video stream player.

Streaming video content should decode properly on AWS.

